

STEP 2023, P2, Q9 - Solution (5 pages; 25/7/24)

(i) 1st Part

Applying N2L to the trailer, in the direction of motion, in the 3 situations:

$$T_1 - \mu R_1 - kMg \sin \alpha = kMa_1, \text{ where } R_1 = kMg \cos \alpha \quad (1)$$

$$T_2 - \mu R_2 = kMa_2, \text{ where } R_2 = kMg \quad (2)$$

$$T_3 - \mu R_3 + kMg \sin \alpha = kMa_3, \text{ where } R_3 = kMg \cos \alpha = R_1 \quad (3)$$

Writing $F = \mu Mg$, eq'ns (1)-(3) become:

$$T_1 - kF \cos \alpha - kMg \sin \alpha = kMa_1 \quad (1')$$

$$T_2 - kF = kMa_2 \quad (2')$$

$$T_3 - kF \cos \alpha + kMg \sin \alpha = kMa_3 \quad (3')$$

[We could have written $F = k\mu Mg$, but it seems advantageous to keep the factor k in all terms, so that the T_i will be in terms of k .]

Applying N2L to the truck, in the direction of motion, in the 3 situations:

$$D - T_1 - Mg \sin \alpha = Ma_1 \quad (4)$$

$$D - T_2 = Ma_2 \quad (5)$$

$$D - T_3 + Mg \sin \alpha = Ma_3 \quad (6)$$

[Avoiding using (2') & (5), as these involve the unwanted T_2

(when trying to establish that $T_1 = T_3$). This also keeps it simple.]

Subtracting (6) from (4) [in order to eliminate D]:

$$T_3 - T_1 - 2Mgsin\alpha = M(a_1 - a_3) \quad (7)$$

Subtracting (3') from (1') [in order to eliminate $kFcos\alpha$]:

$$T_1 - T_3 - 2kMgsin\alpha = kM(a_1 - a_3) \quad (8)$$

Then, eliminating $2Mgsin\alpha$ from (7) & (8) gives:

$$T_1 - T_3 + k(M(a_1 - a_3) + T_1 - T_3) = kM(a_1 - a_3),$$

and hence $(1 + k)(T_1 - T_3) = 0$,

so that $T_1 = T_3$, as required.

2nd Part

Adding eq'ns (4) & (6):

$$2D - T_1 - T_3 = M(a_1 + a_3)$$

Then, substituting for D from eq'n (5):

$$2(Ma_2 + T_2) - T_1 - T_3 = M(a_1 + a_3),$$

so that $M(a_1 + a_3 - 2a_2) = 2(T_2 - T_1)$, as required (as $T_3 = T_1$).

(ii)(a) Subtracting eq'n (2) from eq'n (1):

$$(T_1 - \mu kMgcos\alpha - kMgsin\alpha) - (T_2 - \mu kMg) = kMa_1 - kMa_2$$

so that $T_1 - T_2 = kM(a_1 - a_2 + \mu g \cos \alpha + g \sin \alpha - \mu g)$

Then, from the 2nd Part of (i), $M(a_1 + a_3 - 2a_2) = 2(T_2 - T_1)$,

so that

$$M(a_1 + a_3 - 2a_2) = 2kM(a_1 - a_2 + \mu g \cos \alpha + g \sin \alpha - \mu g)$$

and so

$$a_1 + a_3 - 2a_2 = 2k(a_1 - a_2 + \mu g \cos \alpha + g \sin \alpha - \mu g) \quad (9)$$

Then, subtracting eq'n (2) from eq'n (3), and using the result that

$$T_3 = T_1:$$

$$(T_1 - \mu kMg \cos \alpha + kMg \sin \alpha) - (T_2 - \mu kMg) = kMa_3 - kMa_2,$$

so that $T_1 - T_2 = kM(a_3 - a_2 + \mu g \cos \alpha - g \sin \alpha - \mu g)$,

and so, using $M(a_1 + a_3 - 2a_2) = 2(T_2 - T_1)$ again,

$$a_1 + a_3 - 2a_2 = 2k(a_3 - a_2 + \mu g \cos \alpha - g \sin \alpha - \mu g) \quad (10)$$

Then, from (9) & (10), $a_1 - a_2 + \mu g \cos \alpha + g \sin \alpha - \mu g$

$$= a_3 - a_2 + \mu g \cos \alpha - g \sin \alpha - \mu g,$$

so that $a_1 - a_3 + 2g \sin \alpha = 0$,

$$\text{and hence } g = \frac{a_3 - a_1}{2 \sin \alpha}$$

This shows that $a_3 > a_1$, which is equivalent to $a_3 > \frac{1}{2}(a_1 + a_3)$

The lower inequality is equivalent to $a_1 + a_3 - 2a_2 > 0$,

which, from the 2nd Part of (ii), is equivalent to $T_2 > T_1$.

Thus, the result to prove is: $T_2 > T_1$

From (2), $T_2 - \mu kMg = kMa_2$

and from (5), $D - T_2 = Ma_2$

[This could enable us to obtain an expression for T_2 , free of a_2 . We might be able to use the fact that $D > 0$.]

Then $T_2 - \mu kMg = k(D - T_2)$,

so that $T_2(k + 1) = kD + \mu kMg$

Also, from (1), $T_1 - \mu kMg \cos \alpha - kMg \sin \alpha = kMa_1$,

and from (4), $D - T_1 - Mg \sin \alpha = Ma_1$

Then $T_1 - \mu kMg \cos \alpha - kMg \sin \alpha = k(D - T_1 - Mg \sin \alpha)$

so that $T_1(k + 1) = kD + \mu kMg \cos \alpha$

Then $(T_2 - T_1)(k + 1) = \mu kMg(1 - \cos \alpha) > 0$ (as $0 < \alpha < \frac{\pi}{2}$),

and hence $T_2 > T_1$, as required.

[Note that we haven't used the fact that $\mu < 1$ yet!]

(b) Once again, from (2), $T_2 - \mu kMg = kMa_2$

and from (5), $D - T_2 = Ma_2$,

and adding these gives $D - \mu kMg = (k + 1)Ma_2$

Also, again from (1), $T_1 - \mu kMg \cos \alpha - kMg \sin \alpha = kMa_1$,

and from (4), $D - T_1 - Mg \sin \alpha = Ma_1$,

and adding these gives

$$D - \mu kMg \cos \alpha - kMg \sin \alpha - Mg \sin \alpha = (k + 1)Ma_1,$$

$$\text{Then } (k + 1)M(a_2 - a_1)$$

$$= -\mu kMg + \mu kMg \cos \alpha + kMg \sin \alpha + Mg \sin \alpha$$

$$> kMg(-\mu + \mu \cos \alpha + \sin \alpha)$$

$$> kMg(-\mu + \mu \cos \alpha + \mu \sin \alpha), \text{ as } \mu < 1$$

$$= kMg\mu(\cos \alpha + \sin \alpha - 1)$$

and so we will have shown that $a_1 < a_2$ if we can establish that

$$\cos \alpha + \sin \alpha - 1 > 0 \text{ for } 0 < \alpha < \frac{\pi}{2}$$

$$\text{Now, } (\cos \alpha + \sin \alpha)^2 = \cos^2 \alpha + \sin^2 \alpha + 2\cos \alpha \sin \alpha,$$

$$\text{so that } (\cos \alpha + \sin \alpha)^2 = 1 + \sin(2\alpha) > 1 \text{ for } 0 < \alpha < \frac{\pi}{2},$$

and hence $\cos \alpha + \sin \alpha > 1$, as $\cos \alpha + \sin \alpha > 0$,

and so $\cos \alpha + \sin \alpha - 1 > 0$, as required,

and therefore $a_1 < a_2$.